CEDR TRANSNATIONAL ROAD RESEARCH PROGRAMME

Call 2015

FALCON

Freight And Logistics in a Multimodal Context
WPC Fit for purpose road vehicles to influence modal choice
(performance based standards)
Task 3.4 Extensive Infrastructure Design Criteria Review
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name
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BWIM    Bridge Weigh-in-Motion
LM      Load Model
NA      National Appendix (for the Eurocodes)
WIM     Weigh-in-Motion
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Management Summary

This deliverable called D3.4 has the purpose to summarize the overview of infrastructure design criteria and legislation with the emphasis on roads, bridges and tunnels.

For pavements, there is no European design criteria. So the national design criteria for various European countries have been listed and explained. The parameters involved in these design criteria and to be chosen are parameters linked to the materials or structures, to climatic actions applied on the pavement all over the year and traffic. For traffic, the effect of a traffic or a given vehicle is evaluated through comparison with the effect of equivalent axle loads.

For bridges, European design criteria exist: the Eurocodes (Eurocode 0, Eurocode 1, ... to Eurocode 8). These building codes are applicable all over Europe; in fact, their application is mandatory since 2010. Only partial, safety coefficients (α- factors) vary from one country to another. These factors can be found in the respective national appendixes, some of them are summarized here.

As for tunnels, it has been shown in report D3.2 that only the horizontal geometry of tunnels is designed according to traffic, as would be a road and its pavement. Therefore, the issue with traffic in tunnels is a problem of parking lots and management of truck passing’s through the tunnels.

The design criteria for pavements and bridges can now be used for the definition of Smart Infrastructure Access Policy (task 3.5 of project FALCON).
1. Introduction

This report called D3.4 is the outcome of an infrastructure design criteria review, with focus on pavements, bridges and tunnels. It follows the deliverable D3.2, which is a catalogue of infrastructure elements in Europe. In both reports, the work has been split by infrastructure types, namely pavements, bridges and tunnels.

As already highlighted in the introduction of D3.2, this organisation of the report in categories of infrastructure elements is commonly used in the assessment of heavy vehicle impact on the road network: development of pavement and bridge design codes (series of Eurocodes, from Eurocode 0 to Eurocode 9), European studies on longer and/or heavier trucks ([1], [2] or [3]), and European research projects on the development of new type of trucks ([4] or [5]).

The design criteria that are explained and listed here deal with material parameters, environmental parameters and description of expected traffic loads. For each of the above-mentioned infrastructure elements, this information is given.

In chapter 2, assumptions made for this work are detailed. Then, chapters 3, 4 and 5 deal with the design criteria of respectively pavements, bridges and tunnels, the design of road geometry being dealt with in report 3.3.

2. Assumptions

2.1. Present design codes

As in report D3.2, only infrastructure designed with existing standards and codes are considered.

2.2. Focus on design parameters linked with traffic

Design criteria involve material characteristics (for example elastic modulus for the bituminous material in bituminous pavements), environmental influence (seasonal changes, target temperature) or design traffic.

While discussing all these design parameters in this report, we will focus on traffic design criteria by explaining their definition. Indeed, design traffic (meaning the traffic for which the infrastructure element) has been designed is another concept than assessing the effect of a given vehicle.

In FALCON, the work will be mainly focussed on assessing and comparing the effect of individual vehicles.

2.3. International (European) and national design criteria

This report is supposed deal with international, European-level design criteria and national ones.

But for pavements, there exist no European design criteria.

For bridges on the other hand, design criteria are European, as indicated by the series of Eurocodes which application is mandatory since 2010; for application, national partial safety factors, as indicated in the various national annexes, are applied and these are specific to the country.
3. Pavements

3.1. Pavement design principles

Most countries use so-called mechanistic-empirical pavement design methods, which are similar in their principle. They are based on two main steps:

- A **calculation of the stress-strain response** of the pavement to a reference load (generally defined as the “equivalent standard axle load”, or ESAL), using a multi-layer linear elastic pavement model.
- The **application of several pavement design criteria**, which allow to calculate the number of standard axle loads (ESALs) which can be supported by the pavement before failure (also called the pavement life), in function of the maximum level of stress or strain calculated in each pavement layer.

The design criteria used depend on the type of pavement, and on the nature of the pavement materials:

- For **low traffic pavements**, the design criterion is generally based on the **maximum level of the vertical compressive strain at the top of the subgrade** $\varepsilon_z$. This criterion is defined as a “rutting criterion” of the subgrade, because the level of permanent deformations in the subgrade is strongly related with $\varepsilon_z$.

- For **thick bituminous pavements**, there are generally two design criteria:
  - The first design criterion is based on the **maximum tensile strain at the bottom of the bituminous layers**, $\varepsilon_t$. This criterion is defined as a “fatigue criterion” of the bituminous layers, because it relates the fatigue life of the bituminous material with the maximum tensile strain at the bottom of the bituminous layers, $\varepsilon_t$.
  - The second criterion is the same rutting criterion of the subgrade, based on the maximum vertical strain $\varepsilon_z$ at the top of the subgrade.

- For pavements with layers treated with hydraulic binders, there are two design criteria:
  - The first design criterion is based on the **maximum tensile stress at the bottom of the bituminous treated layers**, $\sigma_t$. This criterion is defined as a “fatigue criterion” of the layers treated with hydraulic binders, because it relates the fatigue life of the hydraulic bound material with the maximum tensile stress $\sigma_t$.
  - The second criterion is again the rutting criterion of the subgrade, based on the maximum vertical strain $\varepsilon_z$ at the top of the subgrade.

All mechanistic pavement design methods are based on several main parameters:

- The **traffic level** and the **service life**, which can be converted into a number of Equivalent Standard Axle Loads (ESAL) that the pavement must support,
- The **bearing capacity of the subgrade** (elastic modulus), which is taken into account in the pavement model and the **mechanical properties** of the pavement materials (elastic modulus, Poisson ratio, fatigue properties...),
• The climate, and in particular the **temperature** (single value, or several climatic periods) considered for the bituminous materials, which have a strongly temperature-dependent behavior,

• A **factor of safety**, (called risk coefficient in the French method), which can be used to adjust the number of loads to failure. For example, in France, a low probability of failure is considered in the design for heavy traffic roads, on which a high level of service must be ensured.

3.1.1. Traffic description.

3.1.1.1. Traffic classes
For classification of roads, and for design, traffic is generally described by **traffic classes**, which represent the daily mean number of heavy vehicles (HV) passing on the road.

In France, heavy vehicles are defined as vehicles with a payload of 5 tons and more, and 8 traffic classes are defined, as described in Table 1.

*Table 1: Definition of traffic classes, in daily number of heavy vehicles, in the French pavement design method.*

These traffic classes cover a wide range, from very low numbers of HV/day (less than 25) to very high numbers (> 5000 HV/day). They correspond approximately to 3 ranges:

• Classes T5, T4, T3 (0 to 150 HV/day) correspond to low traffic roads (secondary roads),
• Classes T2 and T1 correspond to medium traffic roads,
• Classes T0 and more correspond to major roads, with heavy traffic (National roads, motorways).

In Sweden, the design traffic is determined with use of B-WIM (Bridge Weigh-in-Motion) systems which monitor the traffic in a detailed way. Indeed, each truck passing the B-WIM system is recorded, in terms of time of passage, axle loads, distance between axles... This gives an exhaustive view on the traffic at this given location.

In Belgium (Flanders), traffic is described in terms of construction classes, which are linked to the number of equivalent 100-kN standard axle loads, see Table 2. These construction classes are then called B1 to B10.

*Table 2: Construction class, according to the number of equivalent 100-kN standard loads.*
This number of equivalent 100-kN standard axle loads is determined based on the expected traffic on the road structure to be designed.

### 3.1.1.2 Equivalent traffic used for design

For design calculations, the number of heavy vehicles corresponding to the real traffic (with variable vehicle types, and variable axle loads) is generally converted into a number of **Equivalent Standard Axle Loads NE**.

In France, for example, the reference axle is a dual wheel, isolated axle, loaded at 130 kN (maximum legal axle weight). The number of heavy vehicles \( N \) is converted into a number of standard axles \( NE \) using a mean Coefficient of Aggressiveness of the vehicles \( CAM \), using the following equation:

\[
NE = N \times CAM
\]

Therefore, the mean **coefficient of aggressiveness CAM** represents the **mean fatigue damage caused by one heavy vehicle**, compared with the damage caused by the standard axle load. The value of \( CAM \) can be calculated using the real axle load distributions of the real traffic, and depends:

- On the axle and vehicle load distributions
- But also on the type of pavement structure (because the damage caused by one vehicle depends on the characteristics of the pavement structure and of the pavement materials).

The concept of coefficient of aggressiveness \( CAM \) can represent a **practical indicator** for describing the impact of a given vehicle on a given type of pavement, and for comparing the relative aggressiveness of different heavy vehicles.

### 3.1.1.3 Assessment of individual vehicles

For fatigue of concrete pavements, the coefficient of fatigue aggressiveness \( CA_v \) of a vehicle \( v \) is defined by:

\[
CA_v = \frac{d_v}{d_{ref}}
\]  

where:

- \( d_v \) is the fatigue damage produced by the heavy vehicle \( v \) (as defined in report D3.2),
- \( d_{ref} \) is the fatigue damage due to a reference load (for example a 5-axle 40-ton standard vehicle) used as reference for comparison with new vehicle concepts developed in the project.

For rutting (bituminous pavements), COST 334 Study “Effects of Wide Single Tyres and Dual Tyres”, published in 2001 [7] has defined a so-called tyre configuration factor (TCF). The TCF value relates the pavement wear of a given tyre to the pavement wear of a reference tyre. Within different axle categories (steered, driven or towed axle), there is a wide range of TCF values which reflects the fact that there are more and less pavement damaging tyres and tyre configurations as options possible.
The damage contribution of a single passage of an axle is expressed by the so-called axle wear factor (AWF). This AWF is a dimensionless factor relating the damage contribution of a specific tyre at a given axle load to the damage contribution of a single passage of the reference tyre(s) with a reference axle load. Reference for the AWF means a passage of a 10-t axle equipped with 295/80R22,5 tyres mounted as twin assembly. To adjust the axle load effect on pavement damage a load equivalency factor (LEF) was introduced in the COST 334 formulas. If only asphalt roads in the primary road network are considered and only primary rutting as damage cause is taken into account, the pavement damage increases with the power of 2 by axle load.

The sum of all axle wear factors of a truck combination are called vehicle wear factor (VWF). For equal TCF and LEF the higher the number of axles the higher is the vehicle wear factor, but on the other hand the higher the payload can be.

For the same gross vehicle weight, the higher the number of axles the lower is the axle wear factor for each axle and also the vehicle wear factor as sum of all axles.

The performance of a vehicle regarding pavement wear can be calculated by relating the payload to the vehicle wear factor. This performance indicator: 
\[ VWF / \text{Payload} \] is abbreviated in the following as PER (vehicle road wear performance). It can be used for relative comparisons of aggressiveness of different vehicles.

The following formulas are generally used for calculation:

1. Load Equivalence Factor (dimensionless):
   \[ \text{LEF} = (\text{axle load} / 10)^2 \]  
   \[ (2) \]

2. Tyre Configuration Factor (dimensionless):
   \[ \text{TCF} = (\text{tyre width} / 470) - 1.65 \times (\text{tyre diameter} / 1059) - 1.12 \]  
   \[ (3) \]

3. Axle Wear Factor (dimensionless):
   \[ \text{AWF} = \text{TCF} \times \text{LEF} \]  
   \[ (4) \]

4. Vehicle Wear Factor (dimensionless):
   \[ \text{VWF} = \text{SUM} (\text{AWF}) \]  
   \[ (5) \]

5. Vehicle Road Wear Performance (dimensionless):
   \[ \text{PER} = \frac{\text{VWF}}{\text{Payload}} \]  
   \[ (6) \]

### 3.2. Other design parameters

#### 3.2.1. Material characteristics

For bituminous materials and materials treated with hydraulic binders (as concrete pavements), the parameters to be chosen are:

- \( E \): elastic modulus,
- \( \nu \): Poisson ratio,
- \( \varepsilon_6 \): limit tensile strain leading to failure for \( 10^6 \) cycles,
- \( b \): exponent of the fatigue law.
3.2.2. Environmental input

Target temperatures have to be chosen. These are given by national regulations which link the geographic position of the road with the target temperature (and/or seasonal changes) to be considered.

3.2.3. Swedish example

The country (Sweden) is divided into five climate zones (basically from south to north). The year is divided into six seasons (winter, winter-thawing, spring thawing, late spring, summer and autumn) and represented as number of days for each season (giving a sum of 365). The material parameters (the stiffness) for the different layers are affected based on the seasons and climate zone. The stiffness values are given in tables (for each climate zone and season) for many materials. They are also incorporated in the design software (PMS Objekt). All calculations are 2-D Axisymmetric calculations with a circular contact area loading.

All traffic volume is transformed to standard axles (ESAL’s). In Sweden, one ESAL is defined as 100 kN dual tyre axle with 300 mm spacing between the wheels and tyre pressure 800 kPa. The amount of traffic is frequently based on BWIM measurements (usually during a 7-day period) but for many project BWIM measurements are lacking and some predictions are done based on other similar roads. The BWIM measurements are processed to represent a B-factor (similar to truck factor in the US). The B-factor (usually in the range 0.8 – 1.3) is the average load equivalency factor of each heavy vehicle and is calculated based on the fourth power law. The expected AADT and the % share/portion of heavy traffic and traffic growth is used to calculate the total number of ESAL’s (called N100) for the design period.

The accumulation for the design criteria is based on Miner’s rule where calculation is only done once for each season and then summed up for the traffic volume for each season, each year, and finally for the total design period.

3.3. Review of design criteria for pavements

The situation for Europe and various European countries is summarized in Table 3.
Table 3: Review of European pavement design criteria.

<table>
<thead>
<tr>
<th>Pavements</th>
<th>Sweden</th>
<th>Norway</th>
<th>Netherlands</th>
<th>Germany</th>
<th>France (source: [9])</th>
<th>UK</th>
<th>Belgium</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Design period</strong></td>
<td>20 years</td>
<td>20 years (Design Guide “N200 Vegbygging”)</td>
<td>20 years</td>
<td>30 years as a rule, according to German pavement design catalogue RStO 12 (guidelines for the standardization of pavement structures), also according to RDO Asphalt 09 (guidelines for the analytical design of asphalt pavement structures)</td>
<td>20 years</td>
<td>HD 26/06 2.27 For trunk roads including motorways where design traffic is heavy in relation to the capacity of the layout, and in all cases where Whole Life Value is taken into account, 40 year designs must be included as permitted options. 20 year designs may be appropriate for less heavily trafficked schemes or for major maintenance where other site constraints apply. In England, a ‘Departure from Standard’ must be obtained from the Overseeing Organisation for use of 20 year designs. The design traffic in msa should be obtained from HD 24 (DMRB 7.2.1).</td>
<td>20 or 30 years</td>
</tr>
<tr>
<td><strong>Description of ESAL</strong></td>
<td>100 kN axle loading on dual tyres with 800 kPa tyre pressure</td>
<td>Number of equivalent 10 tonne axle loads per lane. Calculated using annual daily heavy vehicle traffic (AADT_Heavy), number of lanes, expected annual traffic growth, length of design period (years), average number of axles per heavy vehicle and</td>
<td>SAL = 100 kN load on axle with SPDM dual wheel sets</td>
<td>ESAL = equivalent number of SAL’s computed from actual traffic loading data</td>
<td>RStO 12: weighted number of equivalent 10-tonnes axle load repetitions in the design period (in the most heavily loaded lanes); Calculated using annual average daily heavy traffic (AADT_Heavy), design period in years, load configuration factor, average number of axles per heavy vehicle, lane factor, lane width factor, slope factor and average annual increase of heavy traffic</td>
<td>RDO Asphalt 09: cumulative number (NE) of passages of reference axle loads (isolated axle with 130-kN dual wheels)</td>
<td>Flanders: Equivalent 100 kN axle loads computed from expected number of lorries, taking into account wander, number of lanes, traffic speed, type of road, type of tyres. Wallonia: number of lorries, spectrum of axle loads, average number of axles per lorry.</td>
</tr>
<tr>
<td>Climatic parameters</td>
<td>permitted axle load.</td>
<td>11 load classes for consideration of truck traffic</td>
<td>Fatigue criteria</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
|---------------------|---------------------|---------------------------------|-----------------
| Yes. Climate seasons (five climatic regions – six seasons per year) | Risk for frost heave based on frost susceptibility of materials on which the road is being built influences thickness of base-layer and frost protection layer. Annual mean temperature and amount of frost (degree-hours). For drainage: Frequency of flooding of a defined magnitude or precipitation of defined intensity. Average temperature: 14°C air temperature for asphalt pavements. Temperature gradient spectrum for concrete roads. | RStO 12: the minimum thickness of frost-resistant road structure is dependent on: - frost susceptibility of the soil in combination with traffic load (load class/construction class) - Local conditions (frost impact: three different frost zones, small-area climate changes, water conditions in the subgrade, position of gradient, drainage of carriageway/execution of border areas) RDO Asphalt 09: Considering of the temperature gradients in all asphalt layers using thirteen different temperature gradients (5 K temperature classes/intervals) and the frequency of occurrence of these temperature gradients (Surface temperature frequency distribution depends on 4 temperature zones), frost protection according to the RStO 12 | RStO 12: The thickness of the road structure shall be specified as to ensure sufficient fatigue resistance to strains from traffic and weather during the intended service life. RDO Asphalt 09: Fatigue function is determined by indirect tensile test. Tensile strain at the bottom of the asphalt concrete is calculated for each season under an ESAL loading and thereafter accumulated for all traffic loading (ESAL’s) using Miner’s law. The design criterion for asphalt pavements is the strain at the bottom of the tensile stressed layers. For pavements with Hydraulic-Binder-Treated Base and Concrete Pavements, “Alternative ‘analytical’”. |
| Wallonia: Thermal gradient within concrete layers, average temperature in each month and its influence on the E-modulus of bituminous layers, depth of frost penetration is checked against freeze index and used for determination of lower layer thicknesses. | HD 26/06 3.1 All material within 450mm of the road surface, where the mean annual frost index (MAFI) of the site is ≥50 must be non frost susceptible in the long-term. Where the MAFI is < 50 the thickness of non-frost susceptible material may be 350 mm. For slower curing HBM appropriate measures must be taken to prevent frost damage in the short term. Further guidance is provided in HD 25. | HD 26/06 3.2 (Bitumen bound materials) The binder content should be sufficient to provide thick enough binder films on the aggregate to create fatigue resistance and achieve durability. Different fatigue laws are used for asphalt or concrete. |
| Fatigue criteria | Tensile strain at the bottom of the asphalt concrete is calculated for each season under an ESAL loading and thereafter accumulated for all traffic loading (ESAL’s) using Miner’s law. Cumulative fatigue damage for asphalt pavements at the bottom of the tensile stressed layers under axle load spectrum and tyre. | No direct criterion, but inherent in other material requirements. Cumulative fatigue damage for asphalt pavements at the bottom of the tensile stressed layers under axle load spectrum and tyre. | RStO 12: The thickness of the road structure shall be specified as to ensure sufficient fatigue resistance to strains from traffic and weather during the intended service life. RDO Asphalt 09: Fatigue function is determined by indirect tensile test. Tensile strain at the bottom of the asphalt concrete is calculated for each season under an ESAL loading and thereafter accumulated for all traffic loading (ESAL’s) using Miner’s law. The design criterion for asphalt pavements is the strain at the bottom of the tensile stressed layers. For pavements with Hydraulic-Binder-Treated Base and Concrete Pavements, “Alternative ‘analytical’”. |

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<table>
<thead>
<tr>
<th>Rutting criteria</th>
<th>The vertical compressive strain is calculated at the top of the subgrade for each season under an ESAL loading and thereafter.</th>
<th>Wheel-track values for Stone Mastic Asphalt (SMA) and Asphalt Concrete (AC).</th>
<th>Limitation of the vertical permanent deformation at the top of unbound layers.</th>
<th>Equivalent tensile stress in the load axle from the surface until the boundary between the asphalt binder course and the asphalt base course.</th>
<th>Limitation of the vertical strain on the top of the concerned courses (subgrade and unbound pavement courses).</th>
<th>HD 26/06 3.3 (Bitumen bound materials) Early age deformation (rutting) in surface and binder course layers may be linked to.</th>
<th>Limitation of the vertical permanent deformation at the top of each of the concerned layers.</th>
</tr>
</thead>
</table>

Cumulative fatigue damage for concrete pavements at the bottom of the concrete layer under axle load spectrum and tyre spectrum and temperature gradient spectrum.

Lateral wander and edge effects are taken into account for both asphalt and concrete.

For pavements with Cement treated Base and Concrete Pavements, the design criterion is the maximum allowable horizontal tensile stress as a result of an extreme axle load.

For pavements with Cement treated Base and Concrete Pavements, the design criterion is the stress at the base of the tensile-stressed layers.

The following fatigue considerations must be taken into account:
- Surface initiated fatigue cracking in thicker/long-life pavements
- Fatigue resistance of asphalt materials
- Excessive stress/strain (combination of magnitude and number of load applications) causing fatigue cracking (typically at the bottom of the base layer) of the asphalt, HBM or concrete material.

Rutting criteria
- The vertical compressive strain is calculated at the top of the subgrade for each season under an ESAL loading and thereafter.
- Wheel-track values for Stone Mastic Asphalt (SMA) and Asphalt Concrete (AC).
- Limitation of the vertical permanent deformation at the top of unbound layers.

Equivalent tensile stress in the load axle from the surface until the boundary between the asphalt binder course and the asphalt base course.

Limitation of the vertical strain on the top of the concerned courses (subgrade and unbound pavement courses).

HD 26/06 3.3 (Bitumen bound materials) Early age deformation (rutting) in surface and binder course layers may be linked to.

Limitation of the vertical permanent deformation at the top of each of the concerned layers.
| Accumulated for all traffic loading using Miner’s law. | Asphalt rutting is not in the design method but only in the material specifications (creep resistance \( fc \)) | Assessing the deformation resistance of the asphalt surface and asphalt binder course mixtures by means of the Cyclic compression test. | Trafficking by slow moving commercial vehicles (e.g. in a contraflow), especially on uphill lengths and when pavement temperatures are high, relatively soon after the materials have been laid (e.g. after major maintenance in the summer). Therefore, such situations should be avoided. Where Hot Rolled Asphalt (HRA) (if permitted) is used, Clause 943 of the Specification (MCHW1) sets out the requirements for performance based surfacing. “Alternative ‘analytical’ pavement design” 4.6 deformation resistance of asphalt materials only, which governs rutting behaviour must be considered when designing pavements. |
4. Bridges

4.1. Methodology for bridge design or assessment

As stated in deliverable D3.2, the structural behaviour of bridges can be summarized by their influence lines. Therefore bridges are designed or assessed by calculating the convolution of the axles loads of the vehicle/traffic/load model with the influence line of the studied effect. Some examples of influence lines are given in Figure 1, where one can see the influence lines for bending moment at first mid-span and middle support, for a 2-span simply supported bridge with both span length equal to 50 metres.

![Influence line of bending moment](image)

Figure 1: Example of influence line of bending moment at first mid-span (x=25 metres) and on support (x=50 metres), for a 2-span simply supported bridge, with both span length equal to 50 metres.

For bridge design against exterior actions (traffic but also climatic actions, like snow, water, ...), one calculates the stresses induced in the structure by the load models given by the European standards. These standards are the Eurocodes:

- Eurocode 0 [1] gives the general framework of bridge design in Europe,
- Eurocode 1 gives the actions to be considered, and more particularly Eurocode 1 – Part 2 [2] gives the traffic actions to be used,
- Eurocodes 2 to 9 explain the methodology to verify that the stresses induced in the structure by the actions chosen in the step before are consistent with convenient structural and material behaviour. For example, Eurocode 3 [3] details how to verify that the stresses induced in the steel structure are not prone to fatigue problems.

These standards are common all over Europe. Only the adjustment factors, called α-factors, may differ from one country to another. That is why each Eurocode i is accompanied by a document called “Eurocode i – National Annex” (specific to each country) which specifies the numerical values of these factors. For more information, [4] summarizes many issues around Eurocodes.
But, if one wants to compare the effect of various vehicles, the methodology is to compute the effects of these vehicles and compare them in terms of extreme loads and fatigue. This methodology has been used during the background works of the US Bridge Formula and the European studies on longer and/or heavier trucks.

In this case, as the evaluation is done in comparison, the influence lines can be theoretical ones. This was also the methodology used during the background works of Eurocode 1.

The following table lists the design criteria ($\alpha$-factors) around Europe, as the abnormal load models.

### 4.2. Traffic load models in Eurocode 1

Load models of Eurocode 1 are only applicable for loaded length inferior to 200 metres. In many countries, this rule is loosened in the National Appendix to span length inferior to 200 metres. Above these values, the load models to be applied have to be defined for each project particularly.

These models have been calibrated carefully in the 1980s, based on traffic recordings of 1986 on highway A6 near Auxerre (France). These models incorporate:

- Impact factor (dynamical behaviour) corresponding to a medium road rugosity (category C in ISO8608:1995, older pavement not maintained),
- Additional impact factor for spans less than 15 metres (corresponding for example to holes in the pavement),
- Covers both the situation where the traffic is flowing with dynamic behaviour a traffic jam of heavy vehicles on the structure.

The characteristic values have been determined statistically for a return period of 1000 years (or probability of exceedance of 5% in 50 years).

Other assumptions have been made:

- The width of lanes have been taken equal to 3.00 metres (instead of physical 3.50metres for roads).
- Any lateral positions of the lanes is possible (in order to cater for any unsuspected situation, like tightening of lanes or works).

Several load models are proposed: originally, LM1 was supposed to be for very heavy truck traffic that is often congested (for example, highways entering cities), and LM2 for more conventional highways. Nevertheless, with the increase in volume and weight of traffic, it is now advised to use LM1 for every highway.

- Load Model 1 (LM1) : Concentrated and uniformly distributed loads, which cover most of the effects of the traffic of lorries and cars. This model should be used for general and local verifications, see Figure 2. The numbers of the lanes are defined: The lane giving the most unfavourable effect is numbered Lane Number 1, the lane giving the second most unfavourable effect is numbered Lane Number 2, etc.
Load Model 2 (LM2): A single axle load applied on specific tyre contact areas which covers the dynamic effects of the normal traffic on short structural members, see Figure 3.

Load Model for abnormal loads: A set of assemblies of axle loads representing special vehicles (e.g. for industrial transport) which can travel on routes permitted for abnormal loads. It is intended for general and local verifications. This load model is defined in the national appendix, and is therefore specific to each country.
To finish, we should mention that Eurocode 1 also defines rules for dispersal of concentrated loads (for example through pavement and a concrete slab), and horizontal forces (braking and acceleration forces, and centrifugal and other transverse forces).
<table>
<thead>
<tr>
<th>Bridges</th>
<th>Sweden</th>
<th>Norway</th>
<th>Netherlands</th>
<th>Germany</th>
<th>France</th>
<th>UK</th>
<th>Belgium</th>
</tr>
</thead>
<tbody>
<tr>
<td>Application of EC1-2</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes</td>
<td>Yes (guidelines of NBN EN 1991-2 ANB table M.1 ANB)</td>
<td></td>
</tr>
<tr>
<td>α-factor</td>
<td>Alpha-factors (LM1 of Eurocode 1): $a_{q1} = 0.6$ All the other alpha-factors = 1.0.</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Use of real traffic data</td>
<td>Yes, only for amount of vehicles. See Table 4</td>
<td>No</td>
<td>Yes, for span length &gt; 200 meters</td>
<td>LM1 valid for loaded lengths up to 1,500m</td>
<td></td>
<td>Yes</td>
<td></td>
</tr>
<tr>
<td>Load models for abnormal loads</td>
<td>Load models now: 1- Total weight: 3240 kN, 18 axles of 180 kN. Distances between axes: 1.50 m (total length: 25.50 m) 2- Total weight: 5400 kN, 15</td>
<td>No</td>
<td>No</td>
<td>Special vehicles defined by the National regulation on special permit vehicles or military vehicles (see Appendix Abnormal loads)</td>
<td>Contained in NA (see Appendix Abnormal loads)</td>
<td>900/150, 1200/150, 1800/150</td>
<td></td>
</tr>
</tbody>
</table>

Examples for abnormal values: 9V80: $6 \times 130 \text{kN}$ separated by $2 \times 1.20 \text{m} + 3 \text{m} + 2 \times 1.20 \text{m}$ |

• First number = total weight kN
• Second number = axle
<p>| | | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>180 kN + 15 · 180 kN. Distances between axles: 14 · 1.50 m + 12 m + 14 · 1.50 m (total length: 54 m) The need to take this into account is considered in each project. Proposed but not yet decided LM3:</td>
<td></td>
<td></td>
</tr>
<tr>
<td>1-</td>
<td>Total weight: 2700 kN, 18 axles of 150 kN. Distances between axles: 1.50 m (total length: 25.50 m)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>2-</td>
<td>Total weight: 4500 kN, 15 · 150 kN + 15 · 150 kN. Distances between axles: 14 · 1.50 m + 12 m + 14 · 1.50 m (total length: 54 m) If decided, every public bridge owned by the counties or the state should be designed for this load model.</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
|   | SV100: 6 × 165 kN separated by 2 × 1.20 m + 3 m + 2 × 1.20 m SV196: 12 × 165 kN separated by 4 × 1.20 m + 2m + 3 × 1.20 m + 4m + 1.6m + 4.4m Also exist SV250, SV350, SV450, SV600. |   |   | weight kN
  • Longitudinal spacing between the axles: 1.5m See Appendix
  Abnormal loads

SV100:
6 × 165 kN separated by 2 × 1.20 m + 3 m + 2 × 1.20 m

SV196:
12 × 165 kN separated by 4 × 1.20 m + 2m + 3 × 1.20 m + 4m + 1.6m + 4.4m

Also exist SV250, SV350, SV450, SV600.
5. **Tunnels**

It has been shown in deliverable D3.2 that only the horizontal geometry of tunnels is designed according to traffic, as would be a road and its pavement, outside a tunnel. Therefore, if one assesses the road geometry and the pavement before and after a tunnel, the results are valid also for the tunnel.

Therefore, the issue with traffic in tunnels is a problem of parking lots and management of truck passing's through the tunnels.

More precisely, the tunnel managers do have basically two ways for dealing with heavy vehicles, especially after the fire at Mont Blanc tunnel:

- They can limit the number of trucks in the tunnels, and therefore the calorific volume, (reduction of risk),
- They can decide to let all heavy vehicles pass through the tunnel at a time timeslot, when there are no other vehicles (reduction of consequences).

There are actually no design guidelines for parking lots in tunnels, but this type of infrastructure is a big issue presently [7] as there have been very important accidents. It is telling to cite the one in the tunnel de la Sierre where a bus has had an impact with the end-wall of such a lay-by on the 13th March 2012. 28 people out of 52 (22 children) have been killed. Therefore the general principle is to include enough drive lanes in the tunnel, so that traffic can flow by even if a vehicle is stopped on the carriage way.

6. **Conclusion**

7. **References**


Appendix

8. Abnormal loads (LM3) for France

The abnormal loads that may be used for designing of road infrastructure can be found here [8]:

Figure 4: Convoy of type C1.

Figure 5: Convoy of type C2.
Figure 6: Convoy of type D.2 F.1

Figure 7: Convoy of type D.2 F.2

Figure 8: Convoy D.3 F.1
Figure 9: Convoy D.3 F.2

Figure 10: Convoy of type E.2 F.1

Figure 11: Convoy E.2 F.2

Figure 12: Convoy of type E.3 F.1
Figure 13: Convoy of type E.3 F.2

Figure 14: Military convoys MC80 (on the left) and MC120 (on the right).

Figure 15: Military loads from a vehicle Leclerc.
9. Abnormal loads in Belgium

For LM3 are used the following configurations:

- 900/150, 1200/150, 1800/150
- 1200/200, 1800/200, 2400/200
- 2400/300, 3600/300

Where:

- First number = total weight kN
- Second number = axle weight kN
- Longitudinal spacing between the axles: 1,5m

Transverse configuration for axles of 150 and 200 kN:

Transverse configuration for axles of 300 kN:
Theoretische aanrakingsoppervlakte van een wiel

Afmetingen in meter
10. Additional Information for the Netherlands

Correction factors related to the amount of heavy vehicles per annum per lane

*Table 4: Correction factors related to the amount of heavy vehicles per annum per lane (The Netherlands)*

<table>
<thead>
<tr>
<th>Aantal vrachtwagens per jaar per rijstrook voor zwaar verkeer $N_{obs}$</th>
<th>$\alpha_{q1}$ en $\alpha_{q1}$</th>
<th>$\alpha_{qr}$</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Lengte van de overspanning of invloedslengte ($L$)</td>
<td>20 m</td>
</tr>
<tr>
<td>$\geq 2000000$</td>
<td>1,0</td>
<td>1,0</td>
</tr>
<tr>
<td>200 000</td>
<td>0,97</td>
<td>0,97</td>
</tr>
<tr>
<td>20 000</td>
<td>0,95</td>
<td>0,94</td>
</tr>
<tr>
<td>2 000</td>
<td>0,91</td>
<td>0,91</td>
</tr>
<tr>
<td>200</td>
<td>0,88</td>
<td>0,87</td>
</tr>
</tbody>
</table>

*Tussengelegen waarden mogen worden geïnterpolleerd.*
11. Additional Information for the United Kingdom

Load model 1 – α factors in the UK national annex to EN 1991-2-2003

Table NA.1 Adjustment factors α₀ and αₚ for Load Model 1

<table>
<thead>
<tr>
<th>Location</th>
<th>α₀ for tandem axle loads</th>
<th>αₚ for UDL loading</th>
</tr>
</thead>
<tbody>
<tr>
<td>Lane 1</td>
<td>α₀₁ = 1,0</td>
<td>αₚ₁ = 0,61 (See note)</td>
</tr>
<tr>
<td>Lane 2</td>
<td>α₀₂ = 1,0</td>
<td>αₚ₂ = 2,2</td>
</tr>
<tr>
<td>Lane 3</td>
<td>α₀₃ = 1,0</td>
<td>αₚ₃ = 2,2</td>
</tr>
<tr>
<td>Other lanes</td>
<td>—</td>
<td>αₚ₄ = 2,2</td>
</tr>
<tr>
<td>Remaining area</td>
<td>—</td>
<td>αₚ₅ = 2,2</td>
</tr>
</tbody>
</table>

NOTE αₚ should be taken as 1,0 for 4.4.1(2) of BS EN 1991-3

Load model 2

β₀ = α₀₁

Load model 3

The following is extracted from the UK national annex to EN 1991-2-2003

**NA.2.16 Load Model 3 (Special Vehicles)**

[BS EN 1991-2:2003, 4.3.4 (1)]

The following defines Load Model 3 and its conditions of use. They do not describe actual vehicles but have been calibrated so that the effects of the nominal axle weights, multiplied by the Dynamic Amplification Factor, represent the maximum effects that could be induced by actual vehicles in accordance with the Special Types General Order (STGO) and Special Order (SO) Regulations.

The choice of the particular STGO or SO model vehicle for the design of structures on motorways, trunk roads and other minor roads should be determined for the individual project.

**NA.2.16.1 Basic models for STGO vehicles**

The following three SV model vehicles simulate vertical effects of different types of STGO vehicles with nominal axle weights not exceeding 16.5 tonnes.

**NA.2.16.1.1 SV80**

The SV80 vehicle is intended to model the effects of STGO Category 2 vehicles with a maximum gross weight of 80 tonnes and a maximum basic axle load of 12.5 tonnes. Figure NA.1(a) gives the basic axle loads, the plan and axle configuration for the SV80 vehicle.
NA.2.16.1.2 **SV100**

The SV100 vehicle is intended to model the effects of STGO Category 3 vehicles with a maximum gross weight of 100 tonnes and a maximum basic axle load of 16.5 tonnes.

Figure NA.1(b) gives the basic axle loads, the plan and axle configuration for the SV100 vehicle.

NA.2.16.1.3 **SV196**

The SV196 model represents the effects of a single locomotive pulling a STGO Category 3 load with a maximum gross weight of 150 tonnes and a maximum basic axle load of 16.5 tonnes with the gross weight of the vehicle train not exceeding 196 tonnes.

Figure NA.1(c) gives the basic axle loads, the plan and axle configuration for the SV196 vehicle.

The wheel loads of all the three SV model vehicles should be uniformly distributed over a square contact area as shown in Figure NA.1.

![Diagram of SV Model Vehicles](image-url)

**Figure NA.1** Basic longitudinal configuration of SV model vehicles

**Key**

1. Outside track and overall vehicle width
2. Critical of 1.2 m or 5.0 m or 9.0 m
3. Direction of travel
Figure NA.1 Basic longitudinal configuration of SV model vehicles
(continued)

(b) SV100 Vehicle

Key
1 = Outside track and overall vehicle width
2 = Critical of 1.2 m or 5.0 m or 9.0 m
3 = Direction of travel

(c) SV196 Vehicle

Key
1 = Outside track and overall vehicle width
2 = Critical of 1.2 m or 5.0 m or 9.0 m
3 = Direction of travel
NA.2.16.2 Basic models for Special Order Vehicles

The following four SOV model vehicles simulate vertical effects of Special Order (SO) vehicles with trailer weights limited to:

i) **SOV-250** – Maximum total weight of SO trailer units up to 250 tonnes

ii) **SOV-350** – Maximum total weight of SO trailer units up to 350 tonnes

iii) **SOV-450** – Maximum total weight of SO trailer units up to 450 tonnes

iv) **SOV-600** – Maximum total weight of SO trailer units up to 600 tonnes.

The longitudinal configuration of the four model vehicles is shown in Figure NA.2. The standard configuration has a trailer with two bogies and two tractors; one pulling and one pushing. However, on structures located on a stretch of road with a gradient steeper than 1 in 25, six tractor units in any combination of pulling and pushing that produces the worst effect, should be used for design.

Figure NA.2 Basic longitudinal configuration of SOV model vehicles
Figure NA.2  **Basic longitudinal configuration of SOV model vehicles**  
*(continued)*

(c) **SOV-450 Vehicle**

![Diagram of SOV-450 Vehicle]

(d) **SOV-600 Vehicle**

![Diagram of SOV-600 Vehicle]

**NOTE.** For simplicity, 6-axle trailer bogies are shown. The actual number of axles of trailer bogie should be that stated above the figure.

The lateral wheel arrangement for the trailer axles of all the SOV model vehicles is shown in Figure NA.3. All the wheels are of equal weight. The contact surface of each wheel should be taken as a square of sides 0.35 m.
The tractor axles of the model vehicles have two wheels, each of equal weight and with square contact areas of side 0.35 m. The outside track and overall width of the vehicle is 3.0 m.

**NA.2.16.3 Dynamic amplification factors**

In determining the load effects of SV and SOV vehicles, the basic axle loads given in Figures NA.1 and NA.2 should be multiplied by the appropriate Dynamic Amplification Factor (DAF) for each axle as given in Table NA.2, depending on the value of the basic axle load.

<table>
<thead>
<tr>
<th>Basic axle load</th>
<th>DAF</th>
</tr>
</thead>
<tbody>
<tr>
<td>100 kN</td>
<td>1.20</td>
</tr>
<tr>
<td>120 kN</td>
<td>1.16</td>
</tr>
<tr>
<td>165 kN</td>
<td>1.12</td>
</tr>
<tr>
<td>180 kN</td>
<td>1.10</td>
</tr>
<tr>
<td>225 kN</td>
<td>1.07</td>
</tr>
</tbody>
</table>

**NA.2.16.4 Application of special vehicle models on the carriageway**

The SV or SOV vehicle loading should be combined with Load Model 1, given in 4.3.2 of BS EN 1991-2, together with the load adjustment factors given in NA.2.12 as follows.

i) Only one SV or SOV model vehicle should be considered on any one superstructure.

ii) The Load Model 1 should be considered to be at the “frequent” values as defined in 4.5 of BS EN 1991-2 and in BS EN 1990, Annex A.2 and its National Annex. The loading should be applied to each notional lane and the remaining area of the bridge deck.
The SV or SOV vehicle can be placed at any transverse position on the carriageway, either wholly within one notional lane or straddling two adjacent lanes, with its side parallel to the kerb. The SV or SOV vehicle should be placed at the most unfavourable position transversely and longitudinally over the loaded length, in order to produce the most severe load effect at the section being considered. The SV or SOV vehicle should be applied on influence lines in its entirety and should not be truncated.

Where the SV or SOV vehicle lies fully within a notional lane the associated Load Model 1 loading should not be applied within 5 m from the centre of outermost axles (front and rear) of the SV or SOV vehicle in that lane as illustrated in Figure NA.4.

Where the SV or SOV vehicle lies partially within a notional lane and the remaining width of the lane, measured from the side of the SV or SOV vehicle to the far edge of the notional lane, is less than 2,5 m [see Figure NA.5(a)], the associated Load Model 1 loading should not be applied within 5 m of the centre of the outermost axles (front and rear) of the SV or SOV vehicle in that lane.

Where the SV or SOV vehicle lies partially within a notional lane and the remaining width of lane, measured from the side of the SV or SOV vehicle to the far edge of the notional lane, is greater than or equal to 2,5 m [see Figure NA.5(b)], the “frequent” value of the uniformly distributed load of the Load Model 1 may be applied over the remaining width of the notional lane (in addition to remaining parts of the lane). The “frequent” value of the tandem system for that notional lane may be applied anywhere along its length.

On the remaining lanes not occupied by the SV or SOV vehicle, the Load Model 1 at its “frequent” value should be applied in accordance with 4.3.2 of BS EN 1991-2.
Figure NA.4  Typical application of SV or SOV and Load Model 1 loading when the SV or SOV vehicle lies fully within a notional lane

Figure NA.5  Typical application of SV or SOV and Load Model 1 loading when the SV or SOV vehicle straddles two adjacent lanes
The notional lanes are located so as to produce the maximum load effect at the part of the structure under consideration in accordance with 4.2.4 of BS EN 1991-2.

## Real traffic data

<table>
<thead>
<tr>
<th>Type</th>
<th>Traffic categories</th>
<th>No. of lanes per carriageway</th>
<th>$N_{obs}$ per lane (millions per year)</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Carriageway layout</td>
<td></td>
<td>Each slow lane</td>
</tr>
<tr>
<td>Motorway</td>
<td>Dual</td>
<td>3</td>
<td>2.0</td>
</tr>
<tr>
<td>Motorway</td>
<td>Dual</td>
<td>2</td>
<td>1.5</td>
</tr>
<tr>
<td>All purpose</td>
<td>Dual</td>
<td>3</td>
<td>n/a</td>
</tr>
<tr>
<td>All purpose</td>
<td>Dual</td>
<td>2</td>
<td>n/a</td>
</tr>
<tr>
<td>Slip road</td>
<td>Single</td>
<td>2</td>
<td></td>
</tr>
<tr>
<td>All purpose</td>
<td>Single</td>
<td>3</td>
<td>1.0</td>
</tr>
<tr>
<td>All purpose</td>
<td>Single</td>
<td>2</td>
<td>0</td>
</tr>
<tr>
<td>Slip road</td>
<td>Single</td>
<td>1</td>
<td>n/a</td>
</tr>
<tr>
<td>All purpose</td>
<td>Single</td>
<td>2</td>
<td>0.5</td>
</tr>
<tr>
<td>Local (low lorry flow)</td>
<td>Single</td>
<td>2</td>
<td>0.05</td>
</tr>
</tbody>
</table>

**NOTE 1** Notes 1 and 2 in BS EN 1991-2 may be disregarded for UK purposes.

**NOTE 2** There is no general relation between traffic categories for fatigue verifications, and the loading classes and associated $a$ factors mentioned in 4.2.2 and 4.3.2.

**NOTE 3** Intermediate values of $N_{obs}$ are not excluded, but are unlikely to have significant effect on the fatigue life.

**NOTE 4** Basing the numbers of heavy goods vehicles on counts of multi-axled lorries ensures a reasonably reliable match between the codified traffic model and the number and types of vehicle that cause the most fatigue damage in the actual traffic.

**NOTE 5** The values presented in Table NA.4 are design values that are intended to reflect approximate road capacities, and they may not match observations of current usage. Traffic flows at a small number of sites may exceed these values, but the differences are unlikely to have a very significant influence on designs.